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How to make contested decisions about time and risk

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Global IQ, Brussels, June 2014

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 Economic evaluation of climate policy has become mired in a debate about appropriate time and risk preferences

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e.g. 'Stern versus Nordhaus'

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 - e.g. 'Stern versus Nordhaus'
- There is no immediate prospect of universal agreement on the specification of time and risk preferences

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Could we nonetheless still find spaces for agreement on which investment to choose?

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- There is no immediate prospect of universal agreement on the specification of time and risk preferences
 - $\blacksquare \approx$ incomplete information about the discount and utility functions
- Could we nonetheless still find spaces for agreement on which investment to choose?
 - Assuming agreement only extends to partially specifying time and risk preferences, spaces for agreement = partial orderings

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Some of the theoretical machinery we require already exists

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- Some of the theoretical machinery we require already exists
 - Stochastic Dominance (Fishburn, 1964,...) and 'Almost' Stochastic Dominance (Leshno and Levy, 2002, and Tzeng et al., 2012, in Mgt. Sci.)

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- But...
 - ...Stochastic Dominance is essentially an a-temporal framework

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 Therefore the conceptual task is to unify the approaches, yielding a theory of *Time-Stochastic Dominance (TSD)*

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 We compare trajectories for global greenhouse gas emissions

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- We compare trajectories for global greenhouse gas emissions
 - Our policies limit the atmospheric stock of CO₂ to various levels, plus 'business as usual'

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- While we are unable to find standard time-stochastic dominance in the data, we find that the toughest emissions targets 'almost' dominate their weaker counterparts

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 - Unlike standard DICE our version is stochastic, with eight random parameters
- While we are unable to find standard time-stochastic dominance in the data, we find that the toughest emissions targets 'almost' dominate their weaker counterparts
 - We can say that only those with 'extreme' preferences would not opt to cut emissions by a large amount

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 In the standard economic model of welfare, time preferences are encoded by a discount function v(t) ∈ V_i, while risk preferences are encoded by a utility function u(x) ∈ U_j

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- In the standard economic model of welfare, time preferences are encoded by a discount function v(t) ∈ V_i, while risk preferences are encoded by a utility function u(x) ∈ U_j
- A space for agreement is a combination of V_i × U_j for which one policy dominates another, i.e. anyone with preferences in this class would prefer the one to the other

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 $U_1\equiv$ all non-decreasing utility functions

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 $U_1\equiv$ all non-decreasing utility functions

 $U_2 \equiv$ all functions in U_1 that also exhibit risk neutrality/aversion

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 $V_1\equiv$ any positive discounting of utility

 $V_2\equiv$ all functions in V_1 that decrease at a decreasing rate

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 We seek to establish dominance relations by looking at differences between cumulative distributions

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■ In Stochastic Dominance these are *cdfs*, i.e. $D^{j}(z) = G^{j}(y) - F^{j}(x)$

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 - In Time-Stochastic Dominance these are *cdfs* of cashflows, i.e. $D_i^j(z, t) = G_i^j(y, t) - F_i^j(x, t)$

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The order of dominance is the number of times the distribution is cumulated/integrated

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• The trouble is dominance can be very hard to demonstrate

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- The trouble is dominance can be very hard to demonstrate
- A classic example is that (simple, i.e. a-temporal) stochastic dominance cannot rank the following alternatives

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- The trouble is dominance can be very hard to demonstrate
- A classic example is that (simple, i.e. a-temporal) stochastic dominance cannot rank the following alternatives
 - F pays out \$0.5 with probability 0.01 and \$1 million with probability 0.99

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2 G pays out \$1 for sure

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2 G pays out \$1 for sure

• Why?
$$D^{j}(z) = G^{j}(y) - F^{j}(x) < 0, \ \forall j, \ x, y \in [0.5, 1)$$

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 - F pays out \$0.5 with probability 0.01 and \$1 million with probability 0.99
 - 2 G pays out \$1 for sure
- Why? $D^{j}(z) = G^{j}(y) F^{j}(x) < 0, \ \forall j, \ x, y \in [0.5, 1)$
- Intuition: broad classes of preferences include extreme risk aversion

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According to this approach:

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- To deal with this we extend the approach of 'Almost' Stochastic Dominance
- According to this approach:
 - Measure the area/volume of violation of dominance, relative to the total area/volume between the distributions

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 Link this violation measure with a restriction on preferences, i.e. functions admissible in V_i × U_i

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- Link this violation measure with a restriction on preferences, i.e. functions admissible in V_i × U_i
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 - Close to zero: small violation and few functions are thrown out, hence large space for agreement

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 Close to 0.5: large violation and many functions are thrown out, hence small space for agreement

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Policies to be evaluated

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CO ₂	γ_1	ε_{1T}	γ_2	ε ₂ τ	λ_{1b}
limit (ppm)					
650	0.00009	0.00003	0.00002	8E-07	0
600	0.00045	0.00003	0.00045	2E-06	6.01E-08
550	0.00092	0.00003	0.00231	2E-06	0.00014
500	0.00188	0.00004	0.00605	3E-06	0.00086
450	0.00388	0.00004	0.01363	4E-06	0.00245

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CO ₂ limit (ppm)	650		600		550		500	
	γ_1	ε_{1T}	γ_1	ε_{1T}	γ_1	ε_{1T}	γ_1	ε_{1T}
600	0.00255	0.00012						
550	0.00351	0.00011	0.01054	0.00034				
500	0.00517	0.00011	0.01260	0.00032	0.01764	0.00050		
450	0.00859	0.00013	0.01870	0.00036	0.02480	0.00052	0.03701	0.00107

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- We do not find standard TSD between any of our policies
- We look instead for Almost TSD, and find it, i.e. we find very small violations of strict TSD

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- We can give the violations an interpretation in terms of the decision-maker's utility and discount functions
 - We use this to argue that only those with 'extreme' preferences would prefer weaker to tougher emissions targets in our set
 - Another way of looking at this is that the debate about time and risk preferences may not be so important after all